

**DVXplorer Lite**  
Discover event based vision



**DVXplorer**  
High resolution



**DAVIS346**  
Simultaneous events and frames



**Event output**

<b>Spatial resolution</b>	320 x 240	640 x 480	346 x 260
<b>Temporal resolution<sup>1</sup></b>	200 $\mu$ s	200 $\mu$ s	1 $\mu$ s
<b>Max throughput</b>	100 MEPS	165 MEPS	12 MEPS
<b>Typical latency<sup>2</sup></b>	<1 ms	<1 ms	<1 ms
<b>Dynamic range</b>	Approx. 90 dB (3-100k lux with 99.9% of pixels respond to 27.5% contrast) Approx. 110 dB (0.3-100k lux with 50% of pixels respond to 80% contrast)	Approx. 90 dB (3-100k lux with 99.9% of pixels respond to 27.5% contrast) Approx. 110 dB (0.3-100k lux with 50% of pixels respond to 80% contrast)	Approx. 120 dB (0.1-100k lux with 50% of pixels respond to 80% contrast)
<b>Contrast Sensitivity</b>	13% (with 50% of pixels respond), 27.5% (with 99.9% of pixels respond)	13% (with 50% of pixels respond), 27.5% (with 99.9% of pixels respond)	14.3% (on), 22.5% (off) (with 50% of pixels respond)

**Frame output**

<b>Spatial resolution</b>		346 x 260
<b>Frame rate</b>		40 FPS
<b>Dynamic range</b>	The camera does not output frames of intensity images. However, similar intensity images can be reconstructed from the event output by our DV software. <sup>3</sup>	55 dB
<b>FPN</b>		4.2 %
<b>Dark signal</b>		18000 e <sup>-</sup> /s
<b>Readout noise</b>		55 e <sup>-</sup>

**IMU**

6-axis (Gyro + Accelerometer), up to 8k Hz sampling rate

**Multi-camera sync**

Supports multi-camera time synchronization via daisy chain connection and external event injection

Other attributes			
Dimensions [mm]	H 40 x W 60 x D 25	H 40 x W 60 x D 25	H 40 x W 60 x D 25
Weight	75 g without lens	100 g without lens	100 g without lens
Lens mount	CS-mount		
Case material	Robust engineering plastic	Anodized aluminum	Anodized aluminum
Mounting options	4-side Whitworth 1/4"-20 female and M3 mounting points		
Connectors	USB 3.0 micro B port with locking screws, fully isolated sync input and output connectors		
Power consumption	<140 mA @ 5 VDC (USB)	<140 mA @ 5 VDC (USB)	<180 mA @ 5 VDC (USB)
Sensor technology	90 nm BSI CIS	90 nm BSI CIS	0.18 μm 1P6M MIM CIS
Pixel pitch [μm]	18μm	9μm	18.5μm
Sensor supply voltage	1.2V, 1.8 V and 2.8 V	1.2V, 1.8 V and 2.8 V	1.8 V and 3.3 V
Certifications	CE certified	CE certified	CE certified

<sup>1</sup> The temporal resolution is characterized by the timestamp unit. In fact, a timestamp unit of 1 μs offers minimum gain over a timestamp unit of 200 μs. For more explanation, please refer to our [white paper](#).

<sup>2</sup> Nominal figure; can be improved with strong lighting/optimised biases.

<sup>3</sup> Please view our [FAQ](#) for further details.

DVS: <https://ieeexplore.ieee.org/document/4444573> P. Lichtsteiner, C. Posch and T. Delbruck, "A 128x128 120dB 15us Latency Asynchronous Temporal Contrast Vision Sensor", IEEE Journal of Solid State Circuits, 43(2) 566-576, 2008

DAVIS: <https://ieeexplore.ieee.org/document/6889103> C. Brandli, R. Berner, M. Yang, S.-C. Liu, and T. Delbruck, "A 240x180 130dB 3us Latency Global Shutter Spatiotemporal Vision Sensor", IEEE Journal of Solid State Circuits, 49(10) 2333-2341, 2014.

### DAVIS346 Limitations:

- In APS GlobalShutter mode, bursts of DSV events can be caused by the capture of an APS frame.
- Due to bandwidth limitations, the DVS event output tends to follow a scanning pattern when under high load.
- The frame output has below average performance in terms of image quality compared to conventional image sensors.
- Color frames are not calibrated, and thus do not faithfully reproduce the real observed color.
- The event output can be destabilized if a strong light source impacts a sensitive spot outside the photosensitive pixel array.